

Self-Learning Knee

#:TGK-5PS0SLKMTX

#### Benefits:

- · High, Polycentric Toe-Clearance in Swing
- Ultra-light Graphite Construction
- Precise Adjustability of Stance Flexion
- · Custom-ICR™ Adjustment
- Trouble-Free Zero Maintenance
- · Smooth Pneumatic "Hydraulic-like" Swing
- Proven Durability & Dependability

#### What is a Matrix?

A Matrix is a self-learning program. The Microprocessor of the SLK Multi-Matrix is pre-programmed with 5 different Matrices. Each Matrix is configured to match the needs and capabilities of Amputees with different weight, activity, and limb lengths profiles. All that is required to program the Multi-Matrix is to select the Matrix that best matches your Patient using the Bluetooth Remote. No computer is required!

### A Tired Amputee is an Unsafe Amputee

Many Transfemoral Patients experience fatigue at some point in their day, affecting their strength to control stability while walking. Any Hydraulic knee system requires high amounts of energy to initiate the swing phase of gait. The many steps in a day accumulate to the point of excessive fatigue. The SLK Multi-Matrix's advanced Pneumatic system requires almost zero energy to initiate swing, keeping your Patient safer all day!



Bluetooth Remote: Enter Desired Matrix, Monitor Battery Charge Level, Adjust Resistance in Manual Mode.

Approved L-Codes\*:

L5856 L5828

### Specifications:

Indication Functional Level K3/K4, Transfemoral or Hip Disarticulation

Item Weight 38.6 oz 1095 g Weight Limit 275 lb 125 kg

Pylon Diameter 30 mm Maximum Flexion Angle 140°

Warranty 2 year Optional 5-year Available



Orders (800) 252-2828 • Technical Support (800) 242-8669 • www.daw-usa.com

© Copyright 2019, DAW Industries, San diego, CA - All Rights Reserved 020819

# 3D MATRIX SELECTION CHART

# MATRIX 1 PATIENT PROFILES

WEIGHT (lb)	ACTIVITY	LENGTH	
220-275	SELECT MATRIX 3		
180-220	LOW	M to L	
140-180	LOW	ALL	

#### MATRIX 1 - EXT./FLEX RESISTANCE MATRIX

ž	<40	1	2	3	3	4	4	5	5
9	<80	2	2	3	3	4	4	5	5
CT	<120	3	3	3	4	4	5	5	6
PA	<160	3	4	4	5	5	5	6	6
Σ	≥160	4	5	5	5	6	6	6	7
GAIT m/s		0.0-0.3		0.6-0.65	0.65-0.7			0.9-1.0	
VELOCITY			SLOW		MODERATE			FAST	

## MATRIX 2 PATIENT PROFILES

WEIGHT (lb)	ACTIVITY	LENGTH		
220-275	SELECT MATRIX 3			
180-220	LOW	SHORT		
140-180	LOW	LONG		

#### MATRIX 2 - EXT./FLEX RESISTANCE MATRIX

*	<40	1	2	3	3	4	4	5	6
9	<80	2	3	3	3	4	5	6	6
CT	<120	3	4	4	4	5	5	6	7
PA	<160	4	5	5	5	6	6	7	8
Σ	≥160	5	5	6	6	6	7	8	8
GAIT m/s		0.0-0.3	0.3-0.6	0.6-0.65	0.65-0.7	0.7-0.8	0.8-0.9	0.9-1.0	>1.0
VELOCITY			SLOW		M	<b>ODERAT</b>	Έ	FA	ST

# MATRIX 3 PATIENT PROFILES

WEIGHT (lb)	ACTIVITY	LENGTH		
220-275	MODERATE	SHORT		
180-220	MODERATE	S to M		
140-180	MODERATE	LONG		

### MATRIX 3 - EXT./FLEX RESISTANCE MATRIX

ž	<40	2	2	3	4	5	5	6	7
10	<80	2	3	3	5	5	6	6	7
Ö	<120	3	4	5	5	6	6	7	8
PA	<160	4	5	5	6	7	7	8	8
Σ	≥160	5	5	6	6	7	8	8	8
GAIT m/s		0.0-0.3	0.3-0.6	0.6-0.65	0.65-0.7	0.7-0.8	0.8-0.9	0.9-1.0	>1.0
VELOCITY			SLOW		MODERATE			FAST	

# MATRIX 4 PATIENT PROFILES

WEIGHT (lb)	ACTIVITY	LENGTH
220-275	MOD/HIGH	M to L
180-220	MOD/HIGH	LONG
140-180	MOD/HIGH	M to L

### MATRIX 4 - EXT./FLEX RESISTANCE MATRIX

ž	<40	3	4	4	5	5	6	7	7
9	<80	4	4	5	5	6	7	7	8
5	<120	4	5	6	6	7	7	8	8
ΡA	<160	5	5	6	6	7	8	8	8
Σ	≥160	5	6	7	7	8	8	8	8
GAIT m/s		0.0-0.3	0.3-0.6	0.6-0.65	0.65-0.7	0.7-0.8	0.8-0.9	0.9-1.0	>1.0
VELOCITY		SLOW			MODERATE			FAST	

# MATRIX 5 PATIENT PROFILES

WEIGHT (lb)	ACTIVITY	LENGTH		
220-275	HIGH	ALL		
180-220	HIGH	M to L		
140-180	HIGH	LONG		

### MATRIX 5 - EXT./FLEX RESISTANCE MATRIX

٠									
ž	<40	4	5	5	5	6	6	7	7
9	<80	5	5	6	6	7	7	8	8
5	<120	5	6	6	7	7	8	8	8
ΒA	<160	6	6	7	7	8	8	8	8
Σ	≥160	7	7	7	8	8	8	8	8
GAIT m/s		0.0-0.3	0.3-0.6	0.6-0.65	0.65-0.7	0.7-0.8	0.8-0.9	0.9-1.0	>1.0
VELOCITY		SLOW			MODERATE			FAST	

\*Impaction is an algorithmic representation of velocities in 3 planes.

